

Optimal Monetary Policy with Heterogeneous Agents: *A Timeless Ramsey Approach*

Eduardo Dávila¹ Andreas Schaab²

¹ Yale and NBER

² Toulouse School of Economics

Motivation

- Heterogeneity in households' exposure to business cycle fluctuations
- Monetary policy has distributional consequences
 - Mounting empirical evidence
Doepke-Schneider (2006), Coibion et al. (2017), Clayton et al. (2018), Ampudia et al. (2018), ...
 - Important lesson from growing heterogeneous-agent New Keynesian (“HANK”) literature

- Fed increasingly taking into account “distributional considerations”

Our revised statement emphasizes that maximum employment is a broad-based and inclusive goal. This change reflects our appreciation for the benefits of a strong labor market, particularly for many in low- and moderate-income communities. — Jerome H. Powell, August 2020

Q: Implications of household heterogeneity for optimal monetary policy?

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- Timeless Ramsey approach to jointly characterize:
 1. Optimal long-run policy
 2. Time consistency and targeting rules
 3. Optimal stabilization policy

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 3. Under commitment, 0 inflation optimal long-run policy
 4. Standard inflation target now augmented by distributional considerations
 5. Time-consistent monetary policy requires a novel distributional target
 6. Divine Coincidence fails in presence of distributional considerations

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- Extend sequence-space approach to Ramsey problems and welfare analysis
Boppart-Krusell-Mitman (2018), Auclert-Bardóczy-Rognlie-Straub (2021)

Model

Overview

- Minimal departure from standard New Keynesian (“RANK”) model
 1. Incomplete markets + idiosyncratic risk *Huggett (1993)*
 2. Wage rigidity *Erceg et al. (2000), Auclert-Rognlie-Straub (2020)*
- Continuous time, $t \in [0, \infty)$
- No aggregate risk: focus on one-time, unanticipated shocks
- Types of shocks: Demand (discount rate) ρ_t , supply (TFP) A_t , and cost-push ϵ_t

Households

Preferences: Households' private lifetime utility is

$$V_0(\cdot) = \max \mathbb{E}_0 \int_0^{\infty} e^{-\int_0^t \rho_s ds} \underbrace{U_t(c_t, n_t)}_{\text{Instantaneous Utility Flow}} dt$$

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Budget constraint: $\dot{a}_t = r_t a_t + z_t w_t n_t + \tau(z_t) - c_t$

- Households trade a bond a_t , borrowing constraint: $a_t \geq \underline{a}$
- Idiosyncratic labor productivity z_t : two-state Markov process
- Lump-sum rebate $\tau(z_t)$ ($= 0$ in equilibrium)

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Cross-sectional distribution: denote joint density $g_t(a, z)$

Labor Markets and Production

Off-the-shelf model of **nominal wage rigidity**: *Erceg et al. (2000)*, *Auclert-Rognlie-Straub (2020)*

- Labor rationing: households work same hours, $n_t = N_t$
- New Keynesian wage Phillips curve:

$$\dot{\pi}_t^w = \underbrace{\rho_t}_{\text{NKPC slope}} \pi_t^w + \frac{\epsilon_t}{\delta} \iint n_t \left(\underbrace{\frac{\epsilon_t - 1}{\epsilon_t}}_{\text{Desired Markup}} \overbrace{(1 + \tau^L)}^{\text{Employment Subsidy}} \underbrace{w_t z u'(c_t) - v'(n_t)}_{\text{Individual Labor Wedge: } \tau_t(a, z)} \right) g_t(a, z) da dz$$

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Production: representative firm produces consumption good $Y_t = A_t N_t$

- Perfect competition + flexible prices: $\frac{W_t}{P_t} = w_t = A_t$ (wages = MRT \neq MRS)

Remaining Model Details

Government:

- Fiscal authority: pays for employment subsidy with lump-sum tax
- Policy instrument: path of interest rates $\{i_t\}_{t \geq 0}$

Market clearing:

Goods:	$Y_t = C_t = \iint c_t(a, z) g_t(a, z) da dz$
Bonds:	$0 = B_t = \iint a g_t(a, z) da dz$

Standard **equilibrium** definition

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Sources of suboptimality:

- | | |
|------------------------------|------------------------|
| (1) Monopolistic competition | (2) Nominal rigidity |
| (3) Labor rationing | (4) Incomplete markets |

Planning Problem

Primal approach: planner picks among implementable competitive equilibria

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The **Standard Primal Ramsey Problem** solves: $\max L(g_0)$, where

$$L = \int_0^{\infty} e^{-\int_0^t \rho_s ds} \left\{ \iint \underbrace{\omega_t(a, z)}_{\text{welfare weights}} U_t(a, z) g_t(a, z) da dz + \right.$$

Primal approach: planner picks among implementable competitive equilibria

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Planner faces **5 implementability conditions:** **micro block**

$$u'(c_t(a, z)) = \partial_a V_t(a, z) \qquad \mathbf{FOC}_t(a, z)$$

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$$\frac{d}{dt} g_t(a, z) = \Lambda_t^{\mathbf{KFE}} g_t(a, z) \quad \mathbf{KFE}_t(a, z)$$

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Planner faces **5 implementability conditions:** **macro block**

$$0 = \iint c_t(a, z) g_t(a, z) da dz - \mathbf{A}_t N_t \quad \mathbf{RC}_t$$

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A **Ramsey plan** is a solution to this problem, i.e., time paths for:

- Allocations and prices: $\{c_t(a, z), V_t(a, z), g_t(a, z), \pi_t^w, N_t\}_{t \geq 0}$
- Policy: $\{i_t\}_{t \geq 0}$
- Multipliers: $\{\phi_t(a, z), \chi_t(a, z), \lambda_t(a, z), \mu_t, \theta_t\}_{t \geq 0}$

Policy Under Discretion

Discretion: control over policy in “*present*”, taking “*future*” (and expectations) as given

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Proposition. (Non-Linear Targeting Rule for Policy under Discretion)

$$\underbrace{\iint \left(zu'(c_t(a, z)) - \frac{v'(N_t)}{A_t} \right) g_t(a, z) da dz}_{\text{Aggregate Labor Wedge}} = \Omega_t \underbrace{\iint au'(c_t(a, z)) g_t(a, z) da dz}_{\text{Distributive Pecuniary Effect}}$$

- Optimal policy trades off **1.** aggregate stabilization (LHS) against **2.** redistribution (RHS)
- Novel force: interest rate policy has **distributive pecuniary effect**
- Aggregate labor wedge < 0 at an optimum: $\iint au'(c_t) g_t da dz = \text{Cov}_{g_t}(a, u'(c_t)) < 0$
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Mechanism / intuition:

- Planner wants to lower real interest rates for redistribution
- Nominal rigidities: lower $i_t \implies$ lower $r_t \implies$ overheated economy with higher inflation

With isoelastic preferences, $u(c) = \frac{1}{1-\gamma}c^{1-\gamma}$ and $v(n) = \frac{1}{1+\eta}n^{1+\eta}$,

$$Y_t = \tilde{Y}_t \times \underbrace{\left(\frac{\epsilon_t}{\epsilon_t - 1} \frac{1}{1 + \tau^L} \right)^{\frac{1}{\gamma+\eta}}}_{\text{Markup Distortion}} \times \underbrace{\left(1 - \Omega_t \frac{\iint au'(c_t(a, z))g_t(a, z) da dz}{\iint zu'(c_t(a, z))g_t(a, z) da dz} \right)^{\frac{1}{\gamma+\eta}}}_{\text{Redistribution}}$$

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HANK: ≥ 1 > 1

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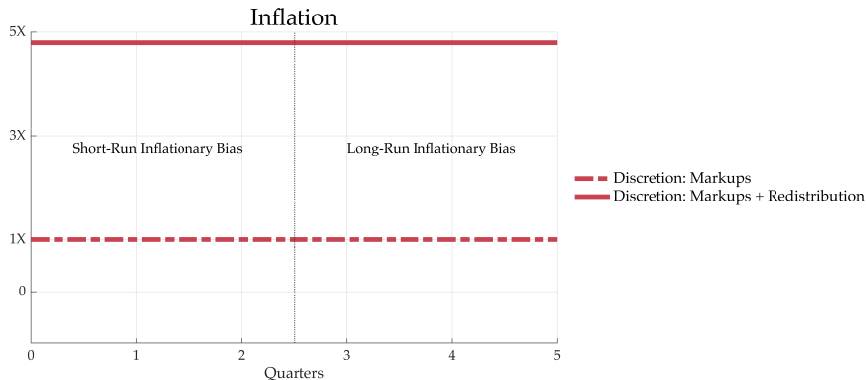
Proposition. In steady state, policy under discretion leads to **inflationary bias**:

$$\pi_{ss}^w = \frac{\epsilon}{\delta} A_{ss} N_{ss} \left[\underbrace{\left(1 - \frac{\epsilon - 1}{\epsilon} (1 + \tau^L) \right) \Lambda_{ss}}_{\text{Markup Distortion: } \geq 0} - \underbrace{\Omega_{ss} \text{Cov}_{g_{ss}(a,z)} \left(a, u'(c_{ss}(a, z)) \right)}_{\text{Redistribution: } > 0} \right]$$

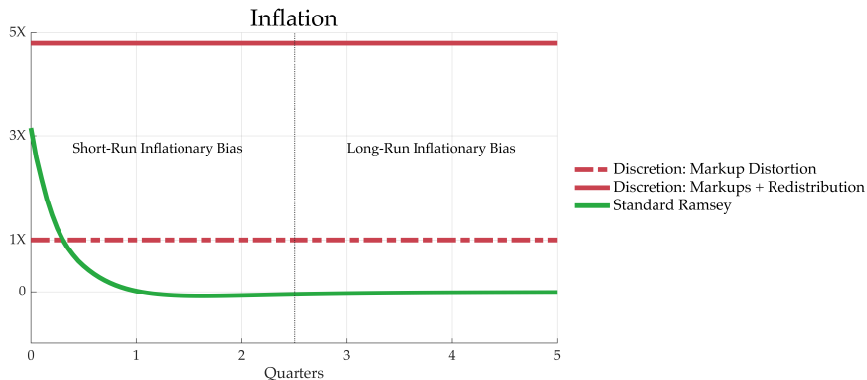
- Redistribution motive exacerbates inflationary bias: $4 \times$ markup distortion term
- **HANK:** Gains from commitment even with appropriate employment subsidy

Timeless Ramsey Approach

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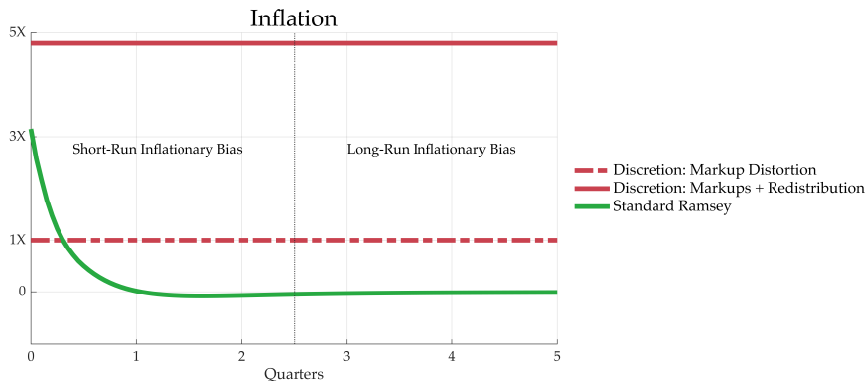
Timeless Ramsey Approach



Step 1: optimal long-run inflation policy

- Policy under commitment converges to 0 inflation
- Standard Ramsey problem resolves inflationary bias in **long run**

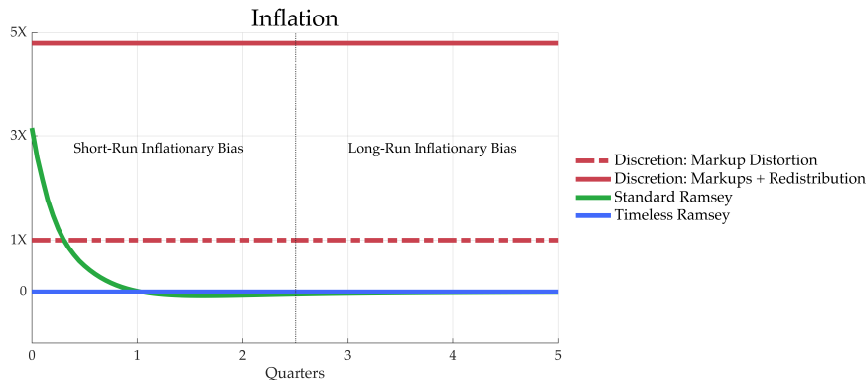
Timeless Ramsey Approach



Step 2: time consistency and targets

- We still have inflationary bias in the short run!
- Two forward-looking constraints \implies planner wants to make promises
 \implies at time 0, no past promises \implies **time inconsistency**

Timeless Ramsey Approach



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- Two forward-looking constraints \implies planner wants to make promises \implies at time 0, no past promises \implies **time inconsistency**
- **Timeless Ramsey problem:** targeting rule to make policy time consistent

Step 2: Timeless Ramsey Problem

Definition. (Timeless Penalties) We define *timeless penalties* as

$$\mathcal{T}(\boldsymbol{\phi}, \boldsymbol{\theta}) = \underbrace{\iint \boldsymbol{\phi}(a, z) V_0(a, z) da dz}_{\text{Distributional Target}} - \underbrace{\boldsymbol{\theta} \pi_0^w}_{\text{Inflation Target}}$$

⇒ Generalizes Marcet-Marimon (2019) to continuous-time heterogeneous-agent economies

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The **Timeless Primal Ramsey Problem** solves: $\max L^{\text{TP}}(g_0, \boldsymbol{\phi}, \boldsymbol{\theta})$, where

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Proposition. Policy under the Timeless Primal Ramsey Problem is time consistent
No inflationary bias in short run or long run

Inflation Target

Proposition. (Inflation Target) Timeless penalty takes form of an inflation target:

$$\underbrace{-\theta_{ss}\pi_0^w}_{\text{Linear inflation target (Walsh, 1995)}}, \text{ where } \theta_{ss} = -\frac{\delta}{\epsilon} \frac{\Omega_{ss}^1 - Y_{ss}^{\gamma+\eta}}{\frac{\epsilon-1}{\epsilon}(1+\tau^L)(1-\gamma)\Omega_{ss}^2 - (1+\eta)Y_{ss}^{\gamma+\eta}}$$

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RANK: distributional wedges collapse to $\Omega_{ss}^1, \Omega_{ss}^2 \rightarrow 1$

- If $\frac{\epsilon-1}{\epsilon}(1+\tau^L) = 1 \implies$ no markup distortion and employment efficient in steady state
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HANK:

- Distributional considerations impact inflation target
- Even with employment subsidy, $\theta_{ss} \neq 0$

Distributional Target

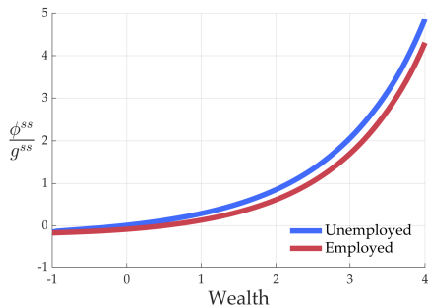
Proposition. (Distributional Target) In HANK, new distributional target required:

$$\iint \phi_{ss}(a, z) V_0(a, z) da dz$$

- Distributional target solves “**promise-keeping Kolmogorov forward equation**”:

$$0 = \Lambda_{ss}^{\text{KFE}} \phi_{ss}(a, z) + \partial_a \chi_{ss}(a, z)$$

- Planner’s promise not to surprise-redistribute is not time consistent
- Like inflation target but for redistribution: $\phi_{ss}(a, z) < 0$ for the poor



Step 3: Optimal Stabilization Policy

Proposition. (Non-Linear Targeting Rule for Stabilization Policy)

$$Y_t = \tilde{Y}_t \times \left\{ \frac{\frac{\epsilon_t}{\epsilon_t - 1} \frac{1}{1 + \tau^L} \Omega_t^1 + \theta_t (1 - \gamma) \frac{\epsilon_t}{\delta} \Omega_t^2}{1 + \theta_t (1 + \eta) \frac{\epsilon_t}{\delta}} \right\}^{\frac{1}{\gamma + \eta}}$$

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RANK: $\Omega_t^1, \Omega_t^2 \rightarrow 1 \implies$ Divine Coincidence if $\frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) = 1$

- **Demand / TFP** shock: $\pi_t^w = 0 \implies \theta_t = 0 \implies Y_t = \tilde{Y}_t$
- **Cost-push** shock: trade-off between inflation and output

Step 3: Optimal Stabilization Policy

Proposition. (Non-Linear Targeting Rule for Stabilization Policy)

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HANK: Divine coincidence generically fails

- Trade-off between inflation / output (aggregate efficiency) and distributional considerations
- Accounting for “**distributional considerations**” comes at cost of **aggregate efficiency**

Sequence-Space Approach to Ramsey Problems

- Extend sequence-space apparatus to optimal policy and welfare analysis
Build on Auclert-Bardóczy-Rognlie-Straub (2021)
- Notation: Path of policy $\mathbf{i} = \{i_t\}_{t \geq 0}$, shocks $\mathbf{Z} = \{\mathbf{A}_t, \boldsymbol{\rho}_t, \boldsymbol{\epsilon}_t\}_{t \geq 0}$, macro aggregates $\mathbf{X} = \{X_t\}_{t \geq 0}$, and aggregate multipliers $\mathbf{M} = \{\theta_t, \mu_t\}_{t \geq 0}$

Proposition. (Sequence-Space Representation of Ramsey Plans) Given g_0 , initial promises $\boldsymbol{\phi}$ and $\boldsymbol{\theta}$, and path of shocks \mathbf{Z} , a Ramsey plan $\mathbf{R} = (\mathbf{X}, \mathbf{M}, \mathbf{i})$ solves

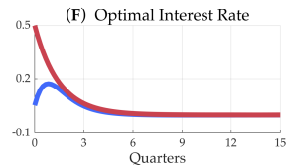
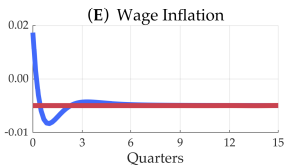
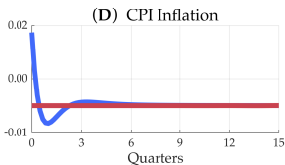
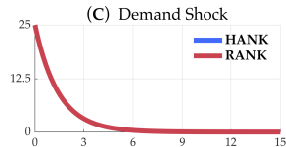
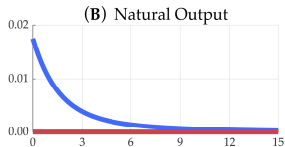
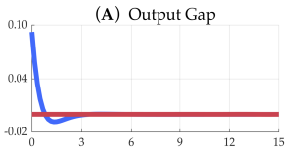
$$\mathcal{R}(\mathbf{X}, \mathbf{M}, \mathbf{i}, \mathbf{Z}) = 0 \quad \implies \quad \mathbf{R} = \mathbf{R}(\mathbf{Z}; g_0, \boldsymbol{\phi}, \boldsymbol{\theta})$$

Proposition. (Sequence-Space Perturbations)

$$d\mathbf{R} = -\mathcal{R}_{\mathbf{R}}^{-1} \mathcal{R}_{\mathbf{Z}} d\mathbf{Z}$$

- $\mathcal{R}_{\mathbf{R}}$ and $\mathcal{R}_{\mathbf{Z}}$ are Jacobians of the Ramsey map \implies extend ABRS fake-news algorithm
- Timeless approach absolutely critical for validity of first-order approximation

Demand Shock



Calibration: $\rho = 0.02$ $\gamma = \eta = 2$ $z \in \{0.8, 1.2\}$ $\epsilon = 10$ $\delta = 100$

Conclusion

- Paper revisits New Keynesian consensus on optimal monetary policy in HANK
- Discretion: novel redistribution motive exacerbates inflationary bias
- Commitment: **Timeless Ramsey approach** to jointly study
 1. Optimal long-run policy
 2. Time consistency and targeting rules → distributional target needed
 3. Optimal stabilization policy
- Extend sequence-space apparatus to Ramsey problems and welfare analysis

- FOC for $g_t(a, z)$ defines **social lifetime value** $\lambda_t(a, z)$ with Bellman:

$$\rho\lambda_t(a, z) = U_t(a, z) + \mathbb{E}_t \left[\frac{d\lambda_t(a, z)}{\lambda_t(a, z)} \right] + \underbrace{\mu_t (c_t(a, z) - A_t z n_t)}_{\text{Individual Contribution to Aggregate Excess Demand}} + \underbrace{\theta_t \frac{\epsilon_t}{\delta} \tau_t(a, z)}_{\text{Individual Contribution to Inflation}}$$

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- Evolution of inflation penalty:

$$\underbrace{\dot{\theta}_t}_{\text{“Inflation Penalty”}} = \delta \pi_t^w + \underbrace{\iint \left(a \partial_a \lambda_t(a, z) g_t(a, z) + a \partial_a V_t(a, z) \phi_t(a, z) \right) da dz}_{= 0}$$

To characterize new inflation target \implies summary statistics for role of heterogeneity

Definition. (Distributional Wedges)

$$\Omega_t^1 = \iint \left(\frac{zu'(c_t)}{u'(Y_t)} + \frac{zu'(c_t)}{u'(Y_t)} \frac{\phi_t}{g_t} + \frac{zu''(c_t)}{u'(Y_t)} \frac{\chi_t}{g_t} \right) g_t da dz$$

$$\Omega_t^2 = \iint \frac{1}{1-\gamma} \left(\frac{zu'(c_t)}{u'(Y_t)} - \gamma \frac{z^2 u''(c_t)}{u''(Y_t)} \right) g_t da dz$$

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Marginal value
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Aggregate efficiency planner / mandate: $\Omega_{1,t}, \Omega_{2,t} \rightarrow 1$ *Dávila-Schaab (2021)*

Optimal Long-Run Inflation Policy

RANK:

$$\dot{\theta}_t^{\text{RA}} = \delta \pi_t^{w, \text{RA}}$$


HANK:

$$\dot{\theta}_t = \delta \pi_t^w + \iint \left(a \phi_t(a, z) \partial_a V_t(a, z) + a g_t(a, z) \partial_a \lambda_t(a, z) \right) da dz$$

Proposition. First-order condition for optimal monetary policy in **HANK**

$$0 = \iint \left(a \phi_t(a, z) \partial_a V_t(a, z) + a g_t(a, z) \partial_a \lambda_t(a, z) \right) da dz$$

- Baseline **HANK** agrees with **RANK** on 0 optimal long-run inflation
- “Necessary condition” for HA to imply non-zero optimal inflation:
Distributional consequences of inflation must be partly orthogonal to nominal interest rate
- Baseline model does not have alternative motives for long-run inflation
Khan-King-Wolman (2003), Schmitt-Grohé-Uribe (2010)

⇒ our approach applies to settings with distributional consequences of long-run inflation 

Proposition 1. (Ramsey Plan)

a) First-order necessary conditions:

$$\mathbf{g} : \quad \rho_t \lambda_t(a, z) = u(c_t) - v(N_t) - \frac{\delta}{2}(\pi_t^2) + \mathcal{A}_t \lambda_t \\ - \mu_t c_t + \vartheta_t \frac{\epsilon_t}{\delta} \frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) \mathbf{A}_t N_t z u'(c_t)$$

$$\mathbf{V} : \quad 0 = \mathcal{A}_t^* \phi_t(a, z) + \partial_a \chi_t(a, z)$$

$$\mathbf{c} : \quad \chi_t(a, z) = - \frac{g_t}{u''(c_t)} \left[\begin{array}{l} u'(c_t) - \mu_t - \partial_a \lambda_t(a, z) \\ + \vartheta_t \frac{\epsilon_t}{\delta} \frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) \mathbf{A}_t N_t z u''(c_t) \end{array} \right]$$

$$\mathbf{N} : \quad 0 = \mu_t - \frac{1}{\mathbf{A}_t} v'(N_t) + \vartheta_t \frac{\epsilon_t}{\delta} \left[\frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) \mathbf{A}_t \Lambda_t - v'(N_t) - v''(N_t) N_t \right] \\ + \iint (z \phi_t(a, z) \partial_a V_t(a, z) + z g_t(a, z) \partial_a \lambda_t(a, z)) da dz$$

$$\pi^w : \quad \dot{\vartheta}_t = \delta \pi_t^w$$

$$\mathbf{i} : \quad 0 = \iint (a \phi_t(a, z) \partial_a V_t(a, z) + a g_t(a, z) \partial_a \lambda_t(a, z)) da dz$$

b) Initial conditions: (1) $\vartheta_0 = 0$ (2) $\phi_0(a, z) = 0$



Implementability Conditions

- **Primal approach:** planner picks among implementable competitive equilibria
Paper also characterizes dual approach
- Find *minimal* set of implementability conditions, associate Lagrange multiplier with each

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Micro block:

$$\rho_t V_t(a, z) = U_t(a, z) + \mathbb{E}_t \left[\frac{dV_t(a, z)}{dt} \right] \quad \phi_t(a, z) \text{HJB}_t(a, z)$$

$$u'(c_t(a, z)) = \partial_a V_t(a, z) \quad \chi_t(a, z) \text{FOC}_t(a, z)$$

$$\frac{d}{dt} g_t(a, z) = \Lambda_t^{\text{KFE}} g_t(a, z) \quad \lambda_t(a, z) \text{KFE}_t(a, z)$$

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Macro block: $0 = A_t N_t - \iint c_t(a, z) g_t(a, z) da dz$ **RC_t**

$$\dot{\pi}_t^w = \rho_t \pi_t^w + \frac{\epsilon_t}{\delta} \left[\frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) w_t \iint z u'(c_t) g_t(a, z) da dz - v'(N_t) \right] N_t \quad \text{NKPC}_t$$

Model Benchmarks and Calibration

Today: main comparison benchmark **RANK limit**

- Limit of no earnings risk: $z_t \rightarrow^P \bar{z} = 1$
- Initialize economy at $g_0(a, z) = \text{Dirac mass point at } (a, z) = (0, \bar{z})$
- **Ongoing work:** quantitative state-of-the-art two-asset HANK model

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RANK limit: non-linear implementability conditions

$$\dot{Y}_t^{\text{RA}} = \frac{1}{\gamma} \left(\dot{i}_t^{\text{RA}} - \pi_t^{w, \text{RA}} + \frac{\dot{A}_t}{A_t} - \rho_t \right) Y_t^{\text{RA}} \quad \text{RA-EE}_t$$

$$\dot{\pi}_t^{w, \text{RA}} = \rho_t \pi_t^{w, \text{RA}} + \frac{\epsilon_t}{\delta} \left[\frac{\epsilon_t - 1}{\epsilon_t} (1 + \tau^L) Y_t^{\text{RA}} u'(Y_t^{\text{RA}}) - v' \left(\frac{Y_t^{\text{RA}}}{A_t} \right) \frac{Y_t^{\text{RA}}}{A_t} \right] \quad \text{RA-NKPC}_t$$

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Calibration: $\rho = 0.02$ $\gamma = \eta = 2$ $z \in \{0.8, 1.2\}$ $\epsilon = 10$ $\delta = 100$

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Skip today: planners in **HANK** and **RANK** agree on 0 optimal long-run inflation 